Appln. No.: 10/020,579

## Amendments to the Specification:

Please replace paragraph [0057] (published in 20020138795 as paragraphs [0062] though [0064]) with the following amended paragraph:

[0057] For better performance, an alternative embodiment of the disclosed method is illustrated in Figure 12. Figure 13. The two signals, x(k) and y(k), are first weighted in the frequency domain before inversely transforming back to time domain. For MDCT transform,

$$x(k) = IMDCT[\alpha(r)X(r)]$$
(7)

$$y(k) = IMDCT[\beta(r)Y(r)]$$
(8)

where  $\alpha(r)$  and  $\beta(r)$  are weighting functions in the frequency domain similar to the weighting functions in equation (1). The replacement signal  $\frac{z(k)}{z(k)}$  is then constructed as

$$z(k) = a(k)x(k) + b(k)y(k), \quad 0 \le k \le 2N - 1$$
(9)

where a(k) and b(k) are weighting functions in the time domain with constraints of

$$a(k) + b(k) = 1, \quad 0 \le k \le 2N - 1$$
 (10)

$$a(k),b(k) \ge 0$$
,  $0 \le k \le 2N-1$  (11)